

# Thyristor Modules

## Thyristor/Diode Modules

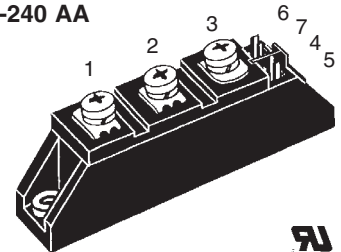
$$I_{TRMS} = 2 \times 80 \text{ A}$$

$$I_{TAVM} = 2 \times 51 \text{ A}$$

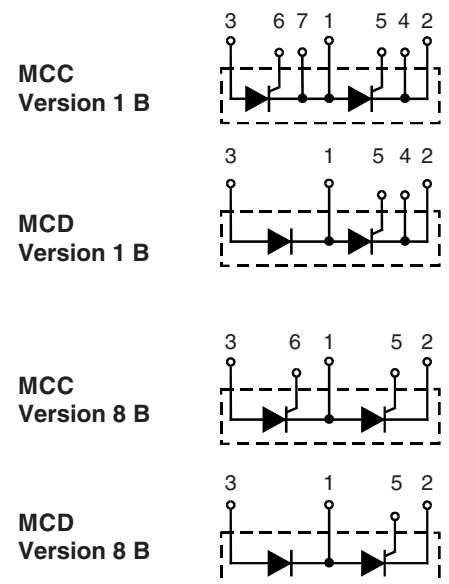
$$V_{RRM} = 800-1800 \text{ V}$$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type      |               |     |           |               |     |  |
|-----------------------------|-----------------------------|-----------|---------------|-----|-----------|---------------|-----|--|
|                             |                             | Version   | 1 B           | 8 B | Version   | 1 B           | 8 B |  |
| 900                         | 800                         | MCC 44-08 | io1 B / io8 B |     | MCD 44-08 | io1 B / io8 B |     |  |
| 1300                        | 1200                        | MCC 44-12 | io1 B / io8 B |     | MCD 44-12 | io1 B / io8 B |     |  |
| 1500                        | 1400                        | MCC 44-14 | io1 B / io8 B |     | MCD 44-14 | io1 B / io8 B |     |  |
| 1700                        | 1600                        | MCC 44-16 | io1 B / io8 B |     | MCD 44-16 | io1 B / io8 B |     |  |
| 1900                        | 1800                        | MCC 44-18 | io1 B / io8 B |     | MCD 44-18 | io1 B / io8 B |     |  |

TO-240 AA



| Symbol                                       | Conditions                                                                                                                                                           | Maximum Ratings                                                       |                                                                                              |
|----------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------|----------------------------------------------------------------------------------------------|
| $I_{TRMS}, I_{FRMS}$<br>$I_{TAVM}, I_{FAVM}$ | $T_{VJ} = T_{VJM}$<br>$T_C = 83^\circ\text{C}; 180^\circ \text{ sine}$<br>$T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$                                           | 80<br>51<br>49                                                        | A<br>A<br>A                                                                                  |
| $I_{TSM}, I_{FSM}$                           | $T_{VJ} = 45^\circ\text{C};$<br>$V_R = 0;$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$                                                | 1150<br>1230                                                          | A<br>A                                                                                       |
|                                              | $T_{VJ} = T_{VJM};$<br>$t = 10 \text{ ms};$<br>$V_R = 0;$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$                                 | 1000<br>1070                                                          | A<br>A                                                                                       |
| $I^2dt$                                      | $T_{VJ} = 45^\circ\text{C};$<br>$V_R = 0;$<br>$T_{VJ} = T_{VJM};$<br>$V_R = 0;$<br>$t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$           | 6600<br>6280<br>5000<br>4750                                          | $\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$ |
| $(di/dt)_{cr}$                               | $T_{VJ} = T_{VJM};$<br>$f = 50\text{Hz}; t_p = 200\mu\text{s};$<br>$V_D = \frac{2}{3} V_{DRM};$<br>$I_G = 0.45 \text{ A};$<br>$di_G/dt = 0.45 \text{ A}/\mu\text{s}$ | repetitive, $I_T = 150 \text{ A}$<br>non repetitive, $I_T = I_{TAVM}$ | 150<br>500<br>$\text{A}/\mu\text{s}$<br>$\text{A}/\mu\text{s}$                               |
| $(dv/dt)_{cr}$                               | $T_{VJ} = T_{VJM};$<br>$R_{GK} = \infty;$ method 1 (linear voltage rise)                                                                                             | $V_{DR} = \frac{2}{3} V_{DRM}$                                        | 1000<br>$\text{V}/\mu\text{s}$                                                               |
| $P_{GM}$                                     | $T_{VJ} = T_{VJM};$<br>$I_T = I_{TAVM};$                                                                                                                             | $t_p = 30 \mu\text{s}$<br>$t_p = 300 \mu\text{s}$                     | 10<br>5<br>W<br>W                                                                            |
| $P_{GAV}$                                    |                                                                                                                                                                      |                                                                       | 0.5<br>W                                                                                     |
| $V_{RGM}$                                    |                                                                                                                                                                      |                                                                       | 10<br>V                                                                                      |
| $T_{VJ}$<br>$T_{VJM}$<br>$T_{stg}$           |                                                                                                                                                                      | -40...+125<br>125<br>-40...+125                                       | $^\circ\text{C}$<br>$^\circ\text{C}$<br>$^\circ\text{C}$                                     |
| $V_{ISOL}$                                   | 50/60 Hz, RMS;<br>$I_{ISOL} \leq 1 \text{ mA};$                                                                                                                      | $t = 1 \text{ min}$<br>$t = 1 \text{ s}$                              | 3000<br>3600<br>V~<br>V~                                                                     |
| $M_d$                                        | Mounting torque (M5)<br>Terminal connection torque (M5)                                                                                                              | 2.5-4.0/22-35<br>2.5-4.0/22-35                                        | Nm/lb.in.<br>Nm/lb.in.                                                                       |
| Weight                                       | typical including screws                                                                                                                                             | 90                                                                    | g                                                                                            |



### Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded  $\text{Al}_2\text{O}_3$ -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1B

### Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

### Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

| Symbol             | Conditions                                                                                                                                                                      | Characteristic Values              |
|--------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------|
| $I_{RRM}, I_{DRM}$ | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$                                                                                                                                | 5 mA                               |
| $V_T, V_F$         | $I_T, I_F = 200 \text{ A}; T_{VJ} = 25^\circ\text{C}$                                                                                                                           | 1.75 V                             |
| $V_{T0}$           | For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )                                                                                                               | 0.85 V                             |
| $r_T$              |                                                                                                                                                                                 | 5.3 mΩ                             |
| $V_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$                                                                                                                                  | 1.5 V                              |
|                    | $T_{VJ} = -40^\circ\text{C}$                                                                                                                                                    | 1.6 V                              |
| $I_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$                                                                                                                                  | 100 mA                             |
|                    | $T_{VJ} = -40^\circ\text{C}$                                                                                                                                                    | 200 mA                             |
| $V_{GD}$           | $T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$                                                                                                                                           | 0.2 V                              |
| $I_{GD}$           |                                                                                                                                                                                 | 10 mA                              |
| $I_L$              | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}; V_D = 6 \text{ V}$<br>$I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$                                            | 450 mA                             |
| $I_H$              | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$                                                                                                                 | 200 mA                             |
| $t_{gd}$           | $T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$<br>$I_G = 0.45 \text{ A}; di_G/dt = 0.45 \text{ A}/\mu\text{s}$                                                                  | 2 μs                               |
| $t_q$              | $T_{VJ} = T_{VJM}; I_T = 120 \text{ A}; t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s}$<br>$V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = 2/3 V_{DRM}$ | typ. 150 μs                        |
| $Q_S$              | $T_{VJ} = T_{VJM}; I_T/I_F = 50 \text{ A}; -di/dt = 0.64 \text{ A}/\mu\text{s}$                                                                                                 | 90 μC                              |
| $I_{RM}$           |                                                                                                                                                                                 | 11 A                               |
| $R_{thJC}$         | per thyristor/diode; DC current per module                                                                                                                                      | 0.53 K/W                           |
| $R_{thJK}$         | per thyristor/diode; DC current per module                                                                                                                                      | 0.265 K/W<br>0.73 K/W<br>0.365 K/W |
| $d_s$              | Creepage distance on surface                                                                                                                                                    | 12.7 mm                            |
| $d_A$              | Strike distance through air                                                                                                                                                     | 9.6 mm                             |
| $a$                | Maximum allowable acceleration                                                                                                                                                  | 50 m/s <sup>2</sup>                |

Optional accessories for module-type MCC 44 version 1 B

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type **ZY 200L** (L = Left for pin pair 4/5) } UL 758, style 1385,

Type **ZY 200R** (R = right for pin pair 6/7) } CSA class 5851, guide 460-1-1

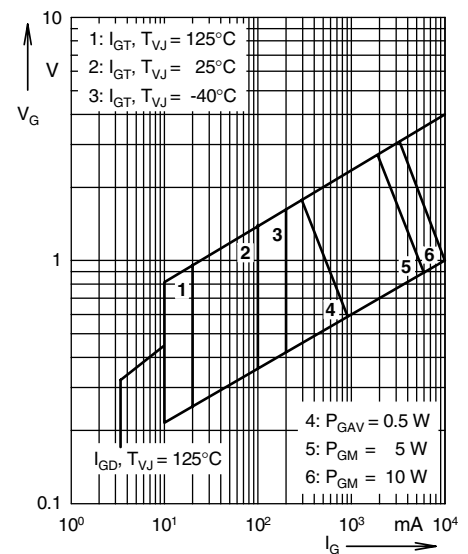


Fig. 1 Gate trigger characteristics

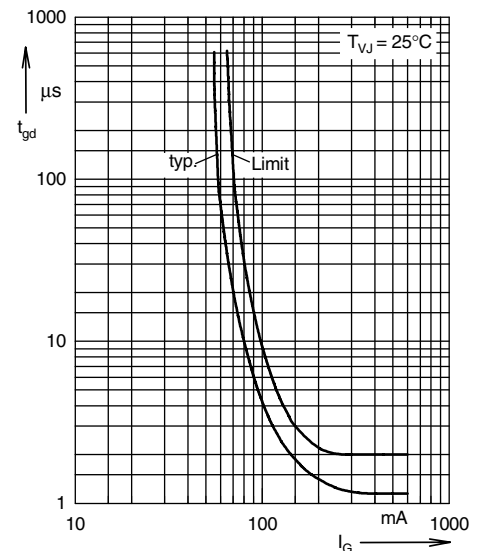
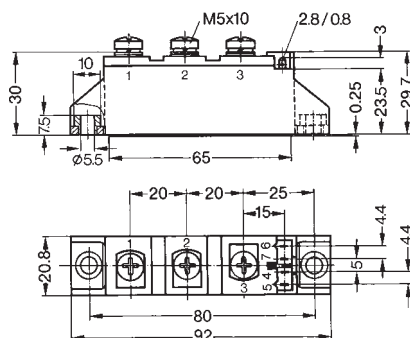


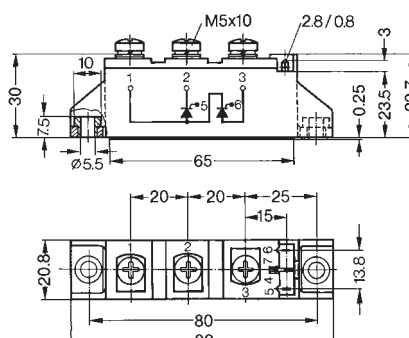
Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

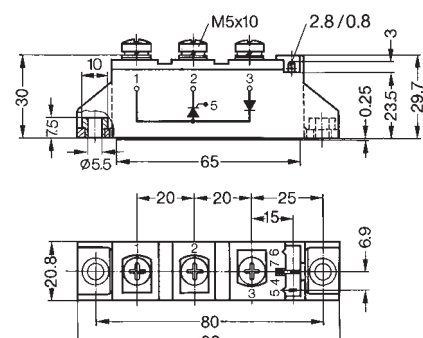
## MCC/MCD Version 1 B



## MCC Version 8 B



## MCD Version 8 B



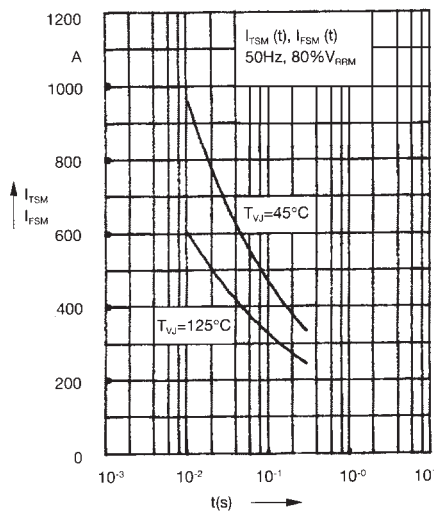


Fig. 3 Surge overload current  
 $I_{TSM}, I_{FSM}$ : Crest value,  $t$ : duration

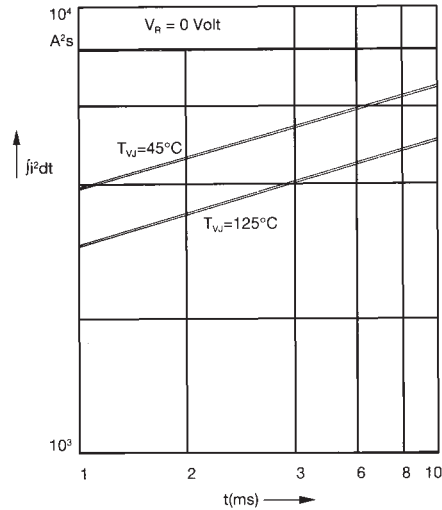


Fig. 4  $j^2dt$  versus time (1-10 ms)

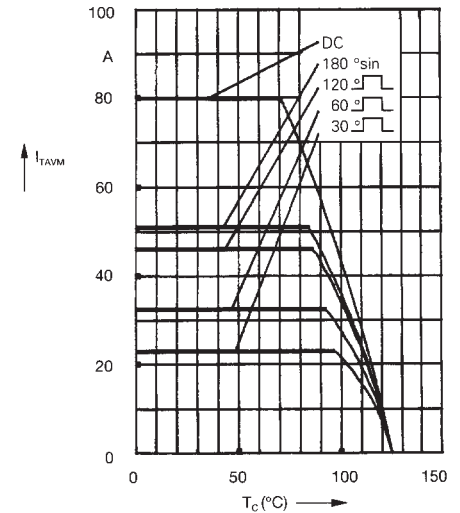


Fig. 4a Maximum forward current at case temperature

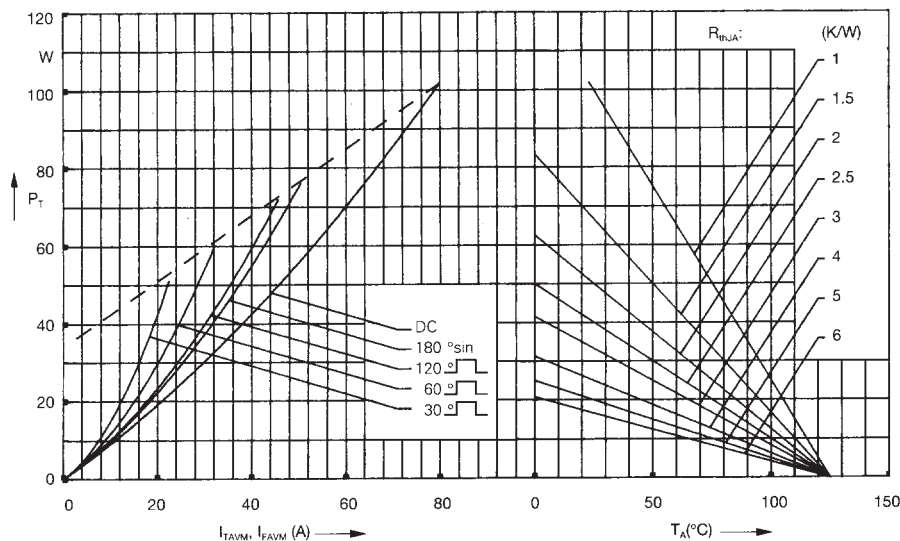


Fig. 5 Power dissipation versus on-state current and ambient temperature (per thyristor or diode)

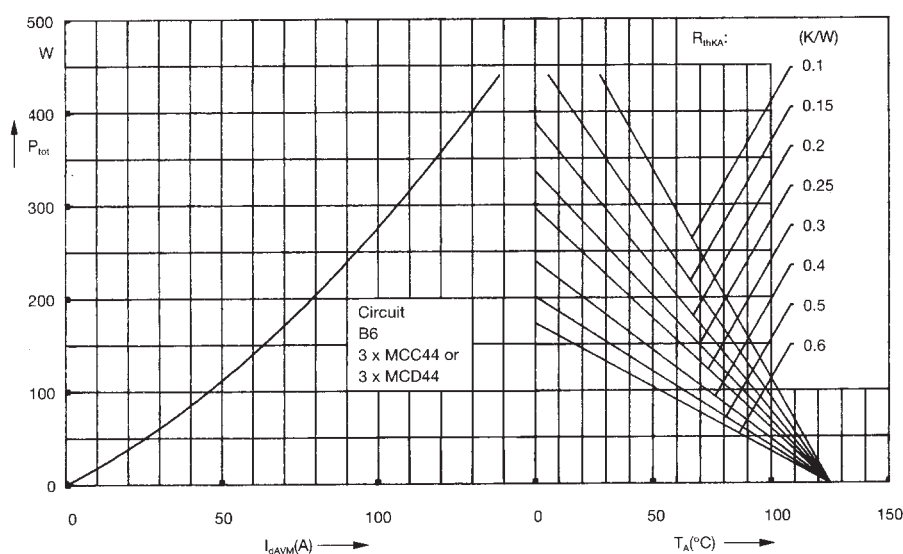


Fig. 6 Three phase rectifier bridge:  
Power dissipation versus direct output current and ambient temperature

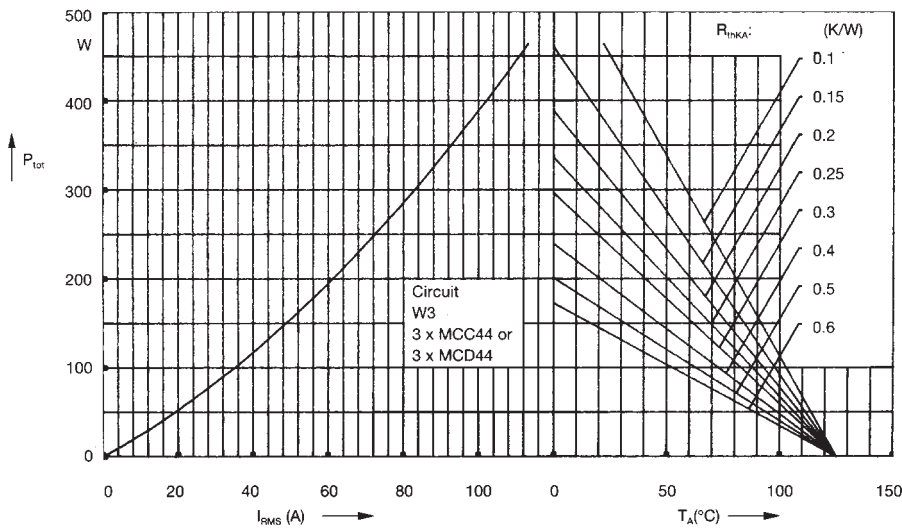


Fig. 7 Three phase AC-controller:  
Power dissipation versus RMS  
output current and ambient  
temperature

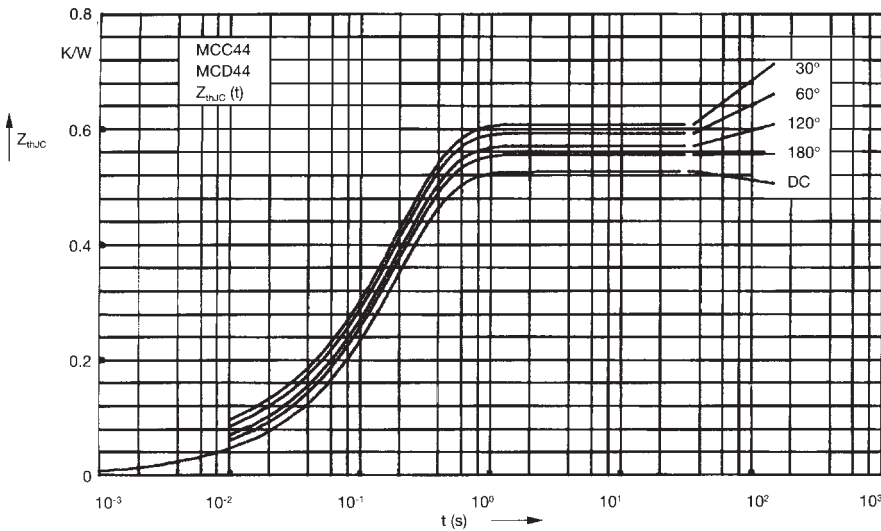


Fig. 8 Transient thermal impedance  
junction to case (per thyristor or  
diode)

$R_{thJC}$  for various conduction angles d:

| d    | $R_{thJC}$ (K/W) |
|------|------------------|
| DC   | 0.53             |
| 180° | 0.55             |
| 120° | 0.58             |
| 60°  | 0.6              |
| 30°  | 0.62             |

Constants for  $Z_{thJC}$  calculation:

| i | $R_{thi}$ (K/W) | $t_i$ (s) |
|---|-----------------|-----------|
| 1 | 0.015           | 0.0035    |
| 2 | 0.026           | 0.02      |
| 3 | 0.489           | 0.195     |

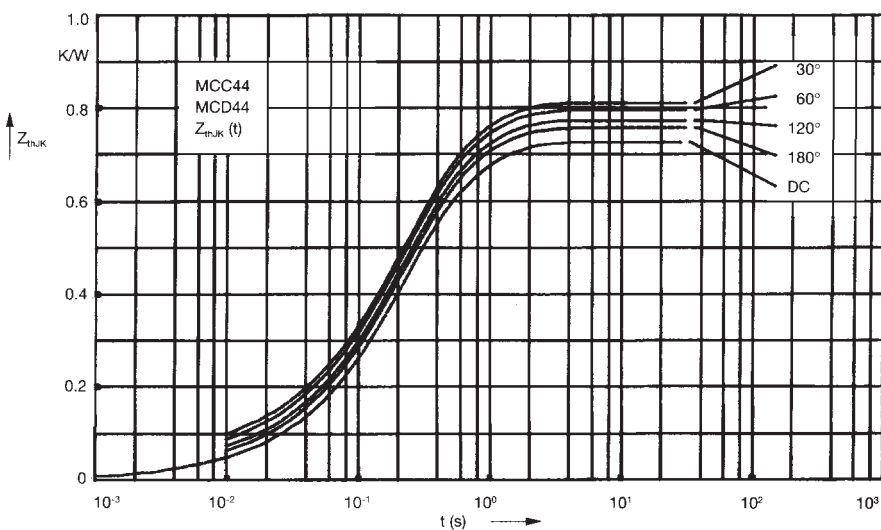


Fig. 9 Transient thermal impedance  
junction to heatsink (per thyristor  
or diode)

$R_{thJK}$  for various conduction angles d:

| d    | $R_{thJK}$ (K/W) |
|------|------------------|
| DC   | 0.73             |
| 180° | 0.75             |
| 120° | 0.78             |
| 60°  | 0.8              |
| 30°  | 0.82             |

Constants for  $Z_{thJK}$  calculation:

| i | $R_{thi}$ (K/W) | $t_i$ (s) |
|---|-----------------|-----------|
| 1 | 0.015           | 0.0035    |
| 2 | 0.026           | 0.02      |
| 3 | 0.489           | 0.195     |
| 4 | 0.2             | 0.68      |